

## **CERTIFICATION FOR TRANSLATION**

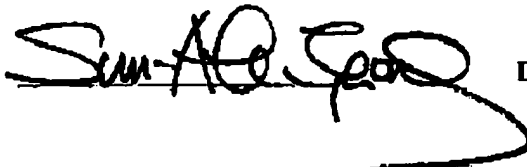
As a below named translator, I hereby declare that:

My residence and citizenship are as stated below next to my name.

I hereby certify that I am conversant with both the English and Korean languages and the document enclosed herewith is a true English translation of a priority document with respect to the Korean patent application No. 7670/2001 filed on 16 February 2001.

**NAME OF THE TRANSLATOR : Sun-Ah JEONG**

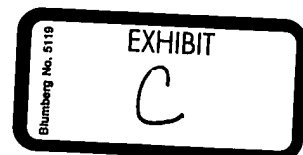
**SIGNATURE :**



**Date : December 3, 2004**

**RESIDENCE : MIHWA BLDG., 110-2, MYONGRYUN-DONG 4-GA, CHONGRO-GU, SEOUL 110-524, KOREA**

**CITIZENSHIP : REPUBLIC OF KOREA**



*Translation of Priority Document*

THE KOREAN INTELLECTUAL  
PROPERTY OFFICE

This is to certify that annexed hereto is a true copy from  
the records of the Korean Industrial property Office of the  
following application as filed

Application Number : Patent Application No. 7670/2001  
Date of Application : February 16, 2001  
Applicant(s) : Samsung Electronics Co., Ltd.

COMMISSIONER

## **[ABSTRACT OF THE DISCLOSURE]**

### **[ABSTRACT]**

Disclosed is a remote monitoring apparatus comprising a control/motoring unit  
5 located in a user's place for remote monitoring; a mobile communication  
terminal with a camera for photographing a subject, for performing a call service  
and an image processing/transmission service including an operation of  
photographing a subject with the camera; and a dynamic support located in a  
remote place to be monitored and having the mobile communication terminal  
10 mounted on the dynamic support itself, for controlling a posture of the mounted  
mobile communication terminal and positional movement of the dynamic support  
itself upon receiving a posture/position control command on the mounted mobile  
communication terminal from the control/monitoring unit via the wireless  
Internet and the mounted mobile communication terminal.

15

20

25

**[TITLE OF THE INVENTION]**

**REMOTE MONITORING APPARATUS USING A MOBILE VIDEOPHONE**

**[BRIEF DESCRIPTION OF THE DRAWINGS]**

5           FIG. 1 is a schematic diagram of a remote monitoring system according to an embodiment of the present invention;

          FIG. 2 is a block diagram of an exemplary mobile videophone according to an embodiment of the present invention;

          FIG. 3 is a detailed block diagram of a dynamic support according to an  
10 embodiment of the present invention; and

          FIG. 4 is a schematic diagram illustrating local (short-distance) wireless communication between dynamic supports, according to an embodiment of the present invention.

          FIG. 5 is a diagram illustrating a protocol stack for real-time  
15 communication of a moving picture between a remotely-situated (remote) mobile videophone and a monitoring system.

**[DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT]**

**[OBJECT OF THE INVENTION]**

20 **[RELATED FIELD AND PRIOR ART OF THE INVENTION]**

          The present invention relates generally to a remote monitoring system, and in particular, to an apparatus for performing remote monitoring using a mobile videophone.

In the conventional remote monitoring system, a camera is mounted on a remotely-situated pan-and-tilt pedestal, which is controlled by wire or controlled wirelessly with a remote controller within a limited radius. A remote place's spot picture photographed by the camera mounted on the pan-and-tilt pedestal is  
5 transmitted by wire to a monitoring terminal such as a computer.

However, the conventional remote monitoring system costs a great deal in installing the camera on the pan-and-tilt pedestal and needs a lot of additional equipments for controlling the remotely-situated camera. In addition, the monitoring terminal should be connected to the camera by wire in order that a  
10 user can view through the monitoring terminal the remote place spot picture photographed by the camera, which makes it difficult to install and maintain the conventional remote monitoring system. Moreover, when the number of remote places to be monitored through the conventional remote monitoring system increases, the scale of the conventional remote monitoring system should be  
15 unacceptably enlarged.

#### [SUBSTANTIAL MATTER OF THE INVENTION]

It is, therefore, an object of the present invention to provide an apparatus for performing remote monitoring using a mobile videophone.

20

It is another object of the present invention to provide a remote monitoring apparatus for inexpensively performing remote monitoring and search using simple equipments.

To achieve the above and other objects, there is provided a remote monitoring apparatus comprising a control/motoring unit located in a user's place for remote monitoring; a mobile communication terminal with a camera for photographing a subject, for performing a call service and an image processing/transmission service including an operation of photographing a subject with the camera; and a dynamic support located in a remote place to be monitored and having the mobile communication terminal mounted on the dynamic support itself, for controlling a posture of the mounted mobile communication terminal and positional movement of the dynamic support itself upon receiving a posture/position control command on the mounted mobile communication terminal from the control/monitoring unit via the wireless Internet and the mounted mobile communication terminal.

#### **[CONSTRUCTION AND OPERATION OF THE INVENTION]**

A preferred embodiment of the present invention will be described herein below with reference to the accompanying drawings. In the following description, well-known functions or constructions are not described in detail since they would obscure the invention in unnecessary detail.

FIG. 1 is a schematic diagram of a remote monitoring system according to an embodiment of the present invention.

Referring to FIG. 1, mobile videophones 10 and 16 each have a camera unit and can compress and transmit a moving picture through long-distance

wireless communication. The mobile videophone 16 mounted on a dynamic support 20 is a mobile communication terminal carried by a user, and is used for photographing and transmitting a spot picture of a remote place. An independent camera 22 mounted on a dynamic support 26 is additionally used for  
5 photographing and transmitting a spot picture of a remote place. The mobile videophone 16 and the independent camera 22 perform a local (short-distance) wireless communication therebetween using Bluetooth modules (BTs) 30 and 40 mounted in the dynamic supports 20 and 26. In an embodiment of the present invention, the BT 30 serves as a master and the BT 40 serves as a slave.

10

The mobile videophone 10 or a PC (Personal Computer) 12 is a control/monitoring unit for remote monitoring, which controls a posture of the mobile videophone 16 and positional movement of the dynamic support 20 through a wireless Internet 14 and demands the mobile videophone 16 to  
15 photograph and transmit a still or moving picture about a desired remote place. In addition, the mobile videophone 10 or the PC 12 controls a posture of the independent camera 22 and positional movement of the dynamic support 26 via the wireless Internet 14, the mobile videophone 16, a connector 18, the dynamic support 20, the BT 30 and the BT 40, and demands the independent camera 22 to  
20 photograph and transmit a still or moving picture about a desired remote place, via the wireless Internet 14, the mobile videophone 16, a connector 18, the dynamic support 20, the BT 30, the BT 40 and a connector 24. Moreover, the mobile videophone 10 or the PC 12 displays on its display a remote place's picture photographed with the mobile videophone 16 and then received through

the wireless Internet.

It is preferable that a WAP (Wireless Application Protocol), which is a Web access protocol in a wireless environment, is used in the wireless Internet 14.

5 The WAP is a wireless protocol, which enables the access to the wire Internet through personal mobile equipments such as a mobile telephone and is now setting down as an application protocol of the future IMT-2000 system. A WAP programming model and a WAP protocol stack according to a WAP specification defined through a WAP forum are well known to those skilled in the art.

10

The connector 18 is a physical device, which physically connects the mobile videophone 16 and the dynamic support 20 to enable the communication between the two. The connector 24 is a physical device, which physically connects the independent camera 22 and the dynamic support 26 to enable the  
15 communication between the two.

Upon receiving a command for controlling a posture of the mobile videocphone 16 and positional movement of the dynamic support 20 from the mobile videophone 10 or the PC 12 via the wireless Internet 14, the mobile  
20 videophone 16 transmits the received command to the dynamic support 20 through the connector 18. The dynamic support 20 then performs an operation corresponding to the received command. In addition, upon receiving from the mobile videophone 10 or the PC 12 via the wireless Internet 14 a command to photograph and transmit a still or moving picture about a desired remote place,



the mobile videophone 16 performs an operation corresponding to the received command. Moreover, upon receiving a command for controlling a posture of the independent camera 22 and positional movement of the dynamic support 26 from the mobile videophone 10 or the PC 12 via the wireless Internet 14, the mobile  
5 videophone 16 transmits the received command to the dynamic support 26 through local wireless communication using the BT 30 and the BT 40. The dynamic support 26 then performs an operation corresponding to the received command.

10        FIG. 2 is a block diagram of an example of the mobile videophones 10 and 16 shown in FIG. 1, which includes a camera unit 104 for photographing a subject.

Referring to FIG. 2, a controller 100 controls an overall operation of the  
15 mobile videophone 10 or 16 for performing various multimedia functions including a voice call function and a subject photography function. In addition, when the user demands a moving picture mode, the controller 100 makes a CODEC 102 decompress and decode still or moving picture data received from the wireless Internet. In a camera mode, the controller 100 makes the CODEC  
20 102 compress still or moving picture data outputted from the camera unit 104 in the JPEG (Joint Picture Expert Group)/MPEG (Moving Picture Expert Group) format and transmits the compressed data to the wireless Internet 14. A first memory 108 stores a program for controlling an overall operation of the mobile videophone 10 or 16, and stores in its predetermined memory area the data

inputted and outputted when an overall operation of the mobile videophone is performed under the control of the controller 100. An RF (Radio Frequency) unit 110 includes a high frequency processing part, an intermediate frequency processing part and a baseband processing part. The RF unit 110 processes, step 5 by step in the above three parts, various multimedia data including voice data and still/moving picture data received through an antenna ANT1 from an external network such as the wireless Internet 14, thereby generating a baseband signal which can be processed in the controller 100. In addition, the RF unit 110 modulates various still/moving picture data outputted from the camera unit 104 10 and compressed by the CODEC 102 into a high frequency signal and transmits the high frequency signal to the wireless Internet 14.

Under the control of the controller 100, an audio unit 112 modulates a voice signal inputted through a microphone MIC into a radio signal and 15 demodulates a radio signal received through the RF unit 110 into an audible signal to output the audible signal through a speaker SPK. In addition, the audio part 112 demodulates a radio audio signal included in still/moving data received from the RF unit 110 in a moving picture mode and outputs the demodulated signal through the SPK. A key input unit 114 has a plurality of numeral keys and 20 a plurality of function keys for a moving picture service and a camera photography function, and generates and outputs key data corresponding to keys pressed by the user to the controller 100. A first display 116 includes a black-and-white LCD (Liquid Crystal Display) for displaying in a general call mode various kinds of information about the mobile videophone in a gray level, and displays

the key data generated in the key input unit 114 and the various information signals of the controller 100. A second display 118 comprises a color TFT-LCD (Thin Film Transistor-LCD) 122 for displaying a moving picture and a LCD driver 124 for driving the color TFT-LCD 122 so as to display, under the control  
5 of the controller 100, various kinds of still/moving picture data outputted from the CODEC 102, and displays in color the still/moving picture data received from the camera unit 104 or the wireless Internet 14 in the camera mode or the moving picture mode.

10       The camera unit 104 captures a subject picture image, and processes a subject picture image photographed in the camera mode into still/moving picture data to provide the processed data to the CODEC 102. More specifically, the subject picture image is provided to a CMOS (Complementary Metal-Oxide Semiconductor) sensor 128 through a lens 126. Then, the CMOS sensor 128  
15 converts a subject light signal passed through the lens 126 into an electrical signal (a photographed picture signal), and performs camera functions such as an exposure function, a gamma function, a gain control function, a white balance function and a color matrix function. An ADC (Analog-to-Digital Converter) 130 converts the photographed picture signal outputted from the CMOS sensor 128  
20 into a digital signal to output the converted photographed picture signal to a DSP (Digital Signal Processor) 132. The DSP 132 processes the converted photographed picture signal into an NTSC (National Television System Committee) or PAL (Phase Alternating by Line) picture signal.

Under the control of the controller 100, the CODEC 102 converts the photographed picture signal (Y, C) generated from the camera unit 104 in the JPEG or MPEG format to then compress the resultant signal at a given ratio, and decompresses and decodes the compressed still/moving picture data received  
5 from the wireless Internet 14 to then provide the resultant signal to the second display 118. The still/moving picture data wirelessly received from an external network such as the wireless Internet 14 may be still/moving picture data received from an engaged counterpart terminal, various kinds of VOD (Video On Demand) data received from Web servers and image contents servers connected  
10 to a mobile switching center (not shown), or still/moving picture data corresponding to the remote place's spot picture photographed with the independent camera 22 or the mobile videophone 16. A second memory 136 connected to the CODEC 102 is usually embodied using an SRAM (Static Random Access Memory), and stores a program for performing various  
15 operations of the CODEC 102. A third memory 138 is usually embodied using a flash memory, and stores a still picture of the picture data received through the lens 126 of the camera unit 104 and the wireless Internet 14.

A USB (Universal Serial Bus) driver 134 and a USB port 120 are used  
20 for communication between the mobile videophone 16 and the dynamic support 20. Specifically, the USB driver 134 converts data corresponding to a posture control command on the mobile videophone 16 and a position control command on the dynamic support 20 in accordance with the USB standard, and transmits/receives the data at a high rate of 12 Mbps or low rate of 1.5 Mbps. The

USB port 120 is a connection port for a cable for transmitting the data received from the controller 100 to the dynamic support 20 and the data received through the connector 18 to the controller 100.

5           FIG. 3 is a detailed block diagram of the dynamic support 20 on which the mobile videophone 16 is mounted. The dynamic support 20 is dynamically movable according to the posture control command on the mobile videophone 16 and the position control command on the dynamic support 20 itself, which are received from the controller 100 through the connector 18. In addition, the  
10 dynamic support 20 transmits a posture control command on the independent camera 22 and a position control command on the dynamic support 26, both provided from the controller 100 through the connector 18, to the dynamic support 26 through the BT 30.

15           Referring to FIG. 3, the dynamic support 20 comprises a controller 200, a first motor driver 202, a first motor 204, a fixing panel 206, a second motor driver 210, a second motor 212, a moving means 214, an interface 218, a key input unit 220 and the BT 30. The first motor driver 202, the first motor 204 and the fixing panel 206 form a block 208 for controlling the posture of the mobile  
20 videophone 16 under the control of the controller 200. The second motor driver 210, the second motor 212 and the moving means 214 constitute a block 216 for moving the positions of the dynamic supports 20 and 26 under the control of the controller 200. The interface 218 is used for communicating with the mobile videophone 16 by the connectors 18 and 24, and comprises elements

corresponding to the USB driver 34 and the USB port 120 of the mobile videophone 16 shown in FIG. 2. The key input unit 220 includes keys for manipulating the dynamic support 20.

5           The BT 30 has an antenna ANT2, and performs a local wireless communication with the dynamic support 26 under the control of the controller 200. As shown in FIG. 1, upon receipt of the posture control command on the independent camera 22 and the position control command on the dynamic support 26 through the connector 18 from the mobile videophone 16, the  
10 dynamic support 20 transmits through the BT 30 the two commands to the BT 40 of the dynamic support 26 on which the independent camera 22 is mounted.

A structure of the dynamic support 26 is identical to that of the dynamic support 20 except that the fixing panel 206 used in the dynamic support 26 has a  
15 structure suitable for mounting the independent camera 22 instead of the mobile videophone 16. In addition, for a case where the independent camera 22 has not a moving-picture compressing function, it is preferable that the controller 200 additionally has an image processing function for the moving-picture compressing function or the dynamic support 22 has an additional unit for  
20 performing the moving-picture compressing function.

The controller 200 drives the fixing panel 206 and/or the moving means 214 according to the posture control command on the mobile videophone 16 and/or the position control command on the dynamic support 20 that are received

through connector 18 and the interface 218. A wheel is a typical example of the moving means 214.

Referring to FIG. 1 again, the mobile videophone 16 is physically  
5 connected to the dynamic support 20 by the connector 18 and a connection port situated at a lower end of the mobile videophone 16. Here, the connection port of the mobile videophone 16 comprises a USB port (i.e., the USB port 120) for securing a sufficient bandwidth for transmission of moving picture data and an existing connection port enabling ascertainment of whether the mobile  
10 videophone 20's battery is charge and whether the mobile videophone 20 is mounted on the dynamic support 20. If both the USB port and the existing connection port are connected to the dynamic support 20, the controller 200 performs the operation described above with reference to FIG. 3.

15 In addition, the independent camera 22 is physically connected to the dynamic support 26 through a USB port for transmission of moving picture data from the independent camera 22 to the dynamic support 26. If the independent camera 22 is physically connected to the dynamic support 26 through the USB port, the dynamic support 26 compresses the moving picture data received from  
20 the independent camera 22 at a given ratio and transmits the compressed moving picture data to the dynamic support 20 through the local wireless communication.

The independent camera 22 is an additional device, which is used when it is difficult to perform a remote monitoring operation using only a spot picture

photographed by the mobile videophone 16. The mobile videophone 16 receives a command relating to an operation of the independent camera 22 from the mobile videophone 10 or the PC 12 and transmits the command to the independent camera 22 through the BTs 30 and 40 of the dynamic supports 20 and 26, and the independent camera 22 then performs an operation corresponding to the command.

FIG. 4 is a schematic diagram illustrating local wireless communication between dynamic supports, according to an embodiment of the present invention. Referring to FIG. 4, a remote monitoring operation is performed using independent cameras 22a, 22b, 22c and 22d mounted on dynamic supports 26a, 26b, 26c and 26d. Here, the BT 30 of the dynamic support 20 serves as a master, and BTs of the dynamic supports 26a, 26b, 26c and 26d serve as slaves.

FIG. 5 is a diagram illustrating a protocol stack for real-time communication of a moving picture between a remote mobile videophone (i.e., the mobile videophone 16) and a monitoring system (i.e., the mobile videophone 10 or the PC 12). A RTP/RTCP (Real-time Transport Protocol/RTP Control Protocol) is used for the real-time communication of the moving picture. The RTP/RTCP is an IETF (Internet Engineering Task Force) standard protocol for real-time data transmission and real-time data transmission control.

Referring to FIG. 5, the protocol stack comprises an IP (Internet Protocol) layer, a UDP/TCP (User Data Protocol/Transmission Control Protocol)



layer on the IP layer, an RTP/RTCP layer on the UDP/TCP, and a video & audio encoder layer on the RTP/RTCP layer.

An operation according to an embodiment of the present invention will  
5 be described in detail with reference to FIGs. 1 to 5.

If an operator (or monitor) commands the mobile videophone 16 to photograph and transmit a moving picture about a desired remote place, using the mobile videophone 10 or the PC 12, then the command is transmitted to the  
10 mobile videophone 16 through the wireless Internet 14. Upon receipt of the command, the mobile videophone 16 photographs the moving picture about the desired remote place and compresses the photographed moving picture data using the CODEC 102. The photographed moving picture is transmitted to the mobile videophone 10 or the PC 12 through the wireless Internet 14. The  
15 transmitted moving picture is displayed on a display of the mobile videophone 10 or a monitor of the PC 12. If the operator desires to monitor the state of the remote place in detail, he gives a posture control command on the mobile videophone 16 and/or a position control command on the dynamic support 20 using a key input unit of the mobile videophone 10 or the PC 12. The posture  
20 control command on the mobile videophone 16 and/or the position control command on the dynamic support 20 are (is) transmitted to the dynamic support 20 via the wireless Internet 14, the mobile videophone 16 and the connector 18. Depending on the posture control command and/or the position control command, the dynamic support 20 properly adjusts the posture of the camera of the mobile

videophone 16 and/or the position of the dynamic support 20 itself.

Meanwhile, when the operator desires to see other nearby place which cannot be monitored through the mobile videophone 16, he gives a command that

5 the independent camera 22 located nearby the mobile videophone 16 be operated so as to monitor the nearby place, using the videophone 10 or the PC 12. That is, if the operator commands the independent camera 22 to photograph and transmit a moving picture about the nearby place, using the mobile videophone 10 or the PC 12, then the command is transmitted to the mobile videophone 16 through the

10 wireless Internet 14. The command transmitted to the mobile videophone 16 is transmitted to the dynamic support 20 through the connector 18 and then transmitted to the dynamic support 26 through a local wireless communication between the BT 30 and the BT 40. The command transmitted to the dynamic support 26 is transmitted to the independent camera 22 through the connector 24.

15 Upon receipt of the command, the independent camera 22 photographs a moving picture about the nearby place and transmits the photographed moving picture to the dynamic support 26 through the connector 24. The dynamic support 26 then compresses the transmitted moving picture using its interior image-processing unit (or the image processing function of the controller 200). The compressed

20 moving picture is transmitted to the dynamic support 20 through a local wireless communication between the BT 40 and the BT 30 and then transmitted to the mobile videophone 16 through the connector 18. The mobile videophone 16 transmits the compressed moving picture to the mobile videophone 10 or the PC 12 through the wireless Internet. Then, the mobile videophone 10 or the PC 12

decompresses the compressed moving picture and displays the decompressed moving picture through its display.

If the operator desires to monitor the state of the nearby place in detail,  
5 he gives a posture control command on the independent camera 22 and/or a position control command on the dynamic support 26 using a key input unit of the mobile videophone 10 or the PC 12. The posture control command on the mobile videophone 16 and/or the position control command on the dynamic support 20 are (is) transmitted to the dynamic support 26 via the wireless Internet  
10 14, the mobile videophone 16, the connector 18, the dynamic support 20, the BT 30 and the BT 40. Depending on the posture control command and/or the position control command, the dynamic support 26 properly adjusts the posture the independent camera 22 and/or the position of the dynamic support 26 itself so as to enable the independent camera 22 to photograph the nearby place in detail.

15

In order to successfully perform a remote monitoring operation, it is preferable that a control operation about the mobile videophone 16 and the independent camera 22 is performed in real time. In the embodiment of the present invention, posture control operations about the mobile videophone 16 and  
20 the independent camera 22 and position control operations about the dynamic supports 20 and 26 are performed in real time according to the RTP shown in FIG. 5. Here, in order to discriminate between moving picture data and a control command, different headers are added to the moving picture data and the control command. In the real-time control operations of the present invention, after the

operator gives a command of positional movement or rotation on the mobile  
videophone 16 or the independent camera 22, an additional performance time for  
the command is not allotted. In the embodiment of the present invention, an  
absolute coordinate value is allotted to the command of the positional movement  
5 or rotation, so that a delay between the operator's control operation and the  
dynamic support's response can be decreased and thereby the operator's  
inconveniences in manipulating the monitoring system can be decreased. For  
example, when the operator presses during two seconds a key for rotating a view  
line direction of the mobile videophone 16's camera counterclockwise, a control  
10 command corresponding to the key are not continuously transmitted to the  
dynamic support 20 for the mobile videophone 16 during the two seconds.  
Instead, a rotation angle corresponding to the two seconds is displayed on the  
operator's monitor, and information about the rotation angle is included in the  
control command and transmitted to the dynamic support 20. When the  
15 independent camera 22 is used for the remote monitoring operation, the dynamic  
support 20 serves as a master and the dynamic support 26 serves as a slave. In  
this case, various control signals are communicated between the dynamic support  
20 and the dynamic support 26 through Bluetooth wireless communication, so as  
to control the posture of the independent camera 22 and the position of the  
20 dynamic support 26.

While the invention has been shown and described with reference to a  
certain preferred embodiment thereof, it will be understood by those skilled in  
the art that various changes in form and details may be made therein without

departing from the spirit and scope of the invention as defined by the appended claims.

#### **[EFFECT OF THE INVENTION]**

5       As described above, a remote monitoring system according to the present invention makes it possible to inexpensively monitor a remote place using a mobile videophone anyone can carry. In addition, the remote monitoring system makes it possible to remotely monitor a vivid state of a dangerous spot using a dynamic support situated in the dangerous spot and a mobile videophone  
10   mounted on the dynamic support.

**[PATENT CLAIMS]**

1. A remote monitoring apparatus comprising:  
a control/motoring unit for remote monitoring;  
a mobile communication terminal with a camera unit for photographing a  
5 subject, for performing a call service and an image processing/transmission  
service including an operation of photographing a subject with the camera unit;  
and

a dynamic support located in a remote place to be monitored and having  
the mobile communication terminal mounted on the dynamic support, for  
10 controlling a posture of the mounted mobile communication terminal and  
positional movement of the dynamic support upon receiving a posture/position  
control command on the mounted mobile communication terminal from the  
control/monitoring unit via a wireless Internet and the mounted mobile  
communication terminal.

15

2. The apparatus as claimed in claim 1, further comprising a  
connector for performing communication between the mounted mobile  
communication terminal and the dynamic support.

20

3. A remote monitoring apparatus comprising:  
a control/motoring unit for remote monitoring;  
a mobile communication terminal with a camera unit for photographing a  
subject, for performing a call service and an image processing/transmission  
service including an operation of photographing a subject with the camera unit;

an independent camera for photographing a subject; and

a first dynamic support located in a remote place to be monitored and having the mobile communication terminal mounted on the first dynamic support, for controlling a posture of the mounted mobile communication terminal and  
5 positional movement of the first dynamic support upon receiving a posture/position control command on the mounted mobile communication terminal from the control/monitoring unit via a wireless Internet and the mounted mobile communication terminal and, upon receiving a posture/position control command on the independent camera from the control/monitoring unit via a  
10 wireless Internet and the mounted mobile communication terminal, transmitting the posture/position control command on the independent camera to the independent camera in accordance with a local wireless communication method.

4. The apparatus as claimed in claim 3, further comprising a second  
15 dynamic support on which the independent camera is mounted, for receiving the posture/position control command from the first dynamic support in accordance with a local wireless communication method and controlling a posture of the mounted independent camera and positional movement of the second dynamic support.

20

5. The apparatus as claimed in claim 4, further comprising a connector for performing communication between the mounted independent camera and the second dynamic support.